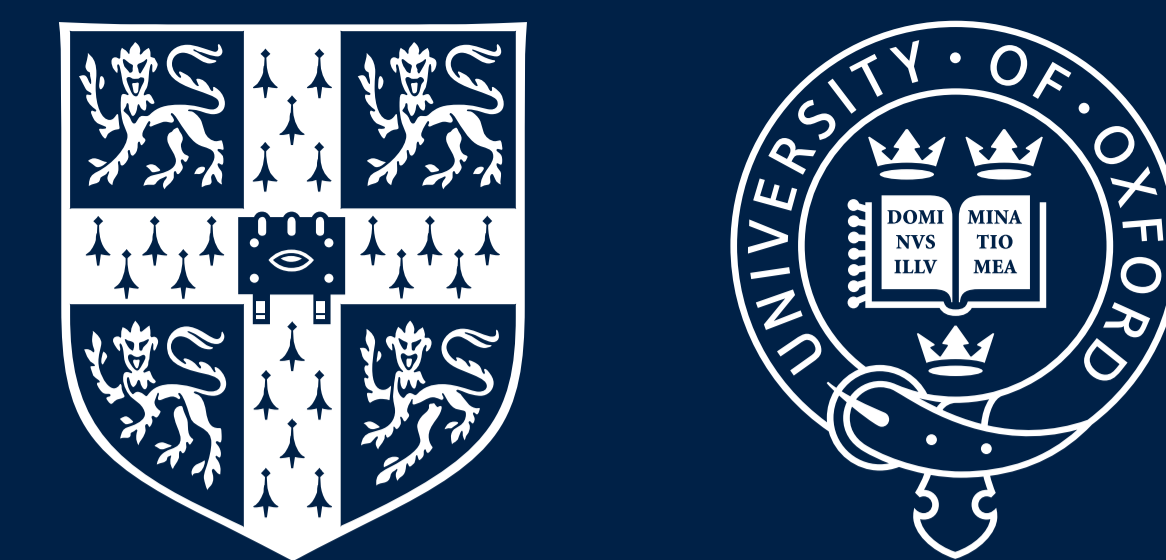


# MODELLING NON-SMOOTH SIGNALS WITH COMPLEX SPECTRAL STRUCTURE

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## GP Convolutional Model (GPCM) [1]

The GPCM as a **linear system**:

$$x \sim \mathcal{GP}(0, \delta(t-t')), \quad h \sim \mathcal{GP}(0, k_h),$$

$$f(t) | h, x = \int_{-\infty}^{\infty} h(t-\tau)x(\tau) d\tau$$

Equivalently, this is a GP with **random kernel**:

$$h \sim \mathcal{GP}(0, k_h),$$

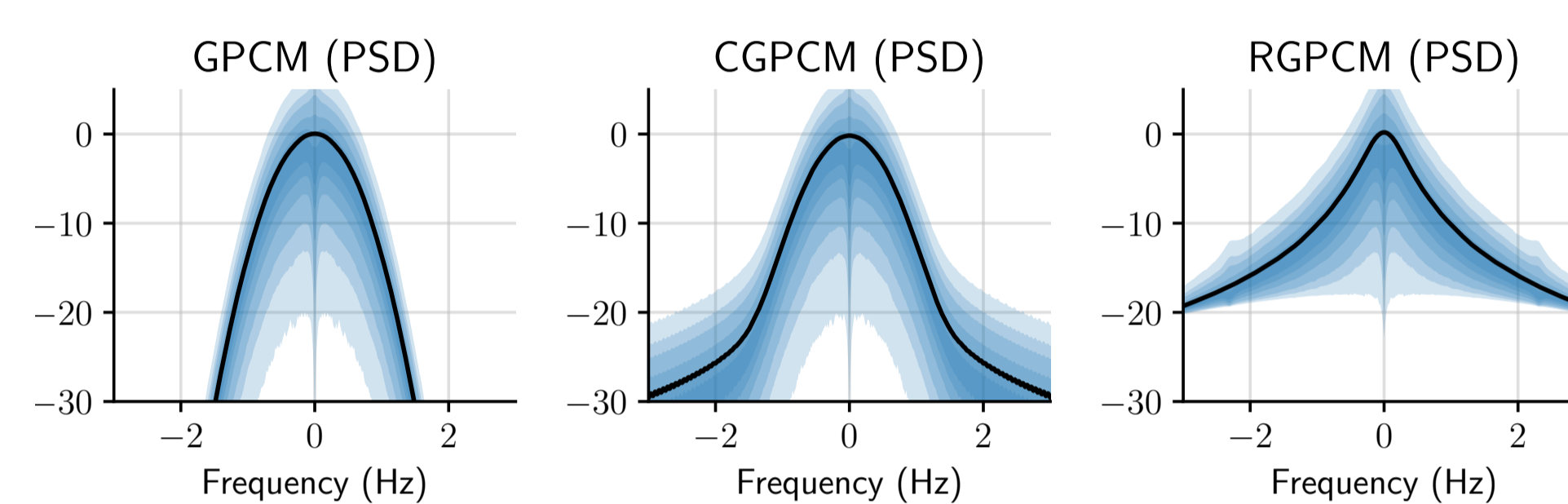
$$f | h \sim \mathcal{GP}\left(0, \int_{-\infty}^{\infty} h((t-t') + \tau)h(\tau) d\tau\right)$$

GPCM: a flexible time-series model class based on a GP with **nonparametric kernel** learned from data by **probabilistic inference**.

## Our contribution

GPCM models **smooth** signals with **rapidly decaying spectrum**. Inference is **mean-field** with poor uncertainty estimates and tedious optimisation of large covariance matrices.

We propose **Causal** and **Rough GPCM**: relaxed smoothness assumptions for a **richer spectrum**. We also relax the mean-field assum. and circumvent variational optimisation.



## The Causal and Rough GPCM

### • GPCM [1]:

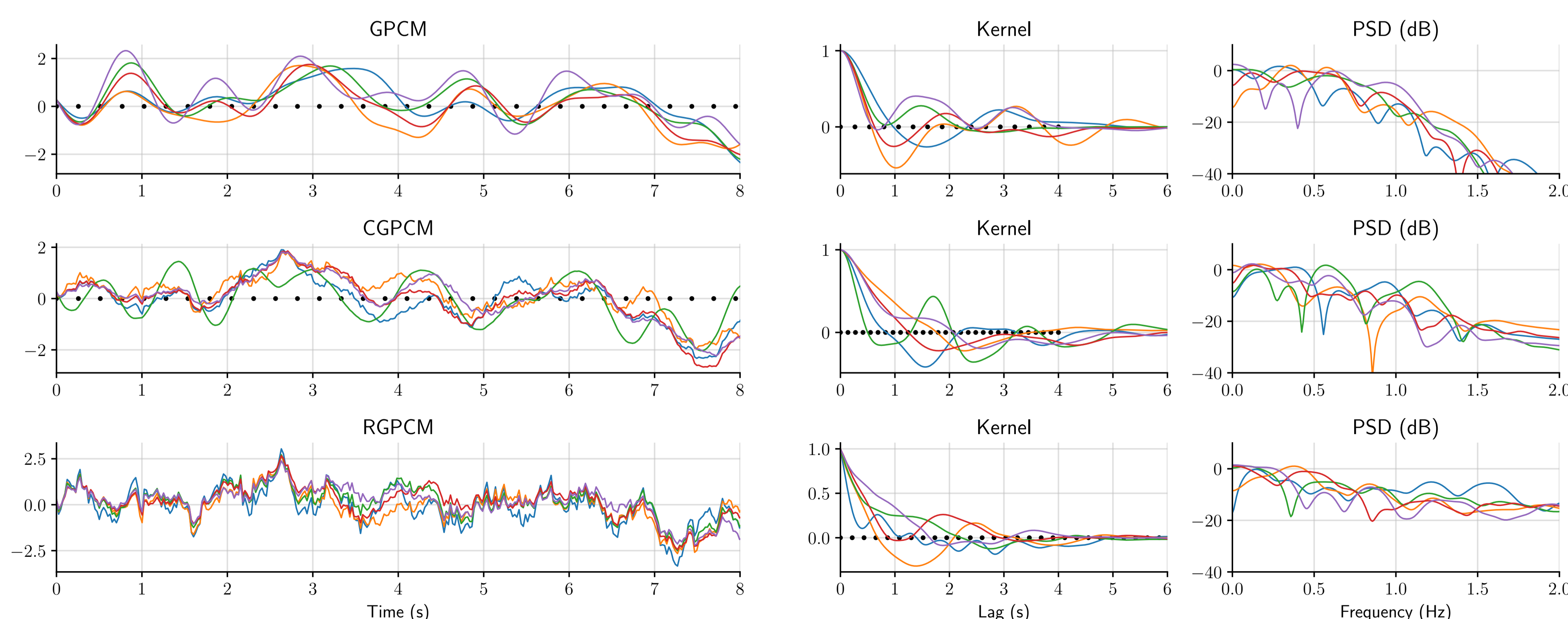
$$f(t) | h, x = \int_{-\infty}^{\infty} e^{-\alpha(t-\tau)^2} h(t-\tau)x(\tau) d\tau, \quad h \sim \mathcal{GP}(0, e^{-\gamma(t-t')^2}), \quad x \sim \mathcal{GP}(0, \delta(t-t'))$$

### • Causal GPCM (CGPCM):

$$f(t) | h, x = \int_{-\infty}^t e^{-\alpha(t-\tau)^2} h(t-\tau)x(\tau) d\tau, \quad h \sim \mathcal{GP}(0, e^{-\gamma(t-t')^2}), \quad x \sim \mathcal{GP}(0, \delta(t-t'))$$

### • Rough GPCM (RGPCM):

$$f(t) | h, x = \int_{-\infty}^t e^{-\lambda|t-\tau|} h(t-\tau)x(\tau) d\tau, \quad h \sim \mathcal{GP}(0, \delta(t-t')), \quad x \sim \mathcal{GP}(0, e^{-\lambda|t-t'|})$$



**Left:** Prior samples of  $f$  to demonstrate smoothness (GPCM, top) and non-differentiability (C/RGPCM, middle and bottom). **Right:** Corresponding samples from kernel and spectrum.

## Variational inference beyond mean-field

**Structured** approximate posterior:

$$p_{\theta}(h, x, \mathbf{u}, \mathbf{z} | \mathbf{y}) \approx p_{\theta}(h | \mathbf{u})p_{\theta}(x | \mathbf{z})q(\mathbf{u}, \mathbf{z})$$

with  $\mathbf{u}$  and  $\mathbf{z}$  interdomain inducing points; VFFs [2] for  $\mathbf{z}$ . **Optimal**  $q^*$  from evidence lower bound:

$$q^*(\mathbf{u}, \mathbf{z}) = \operatorname{argmax}_q \mathcal{F}_{\theta}(q) \leq \log p_{\theta}(\mathbf{y}).$$

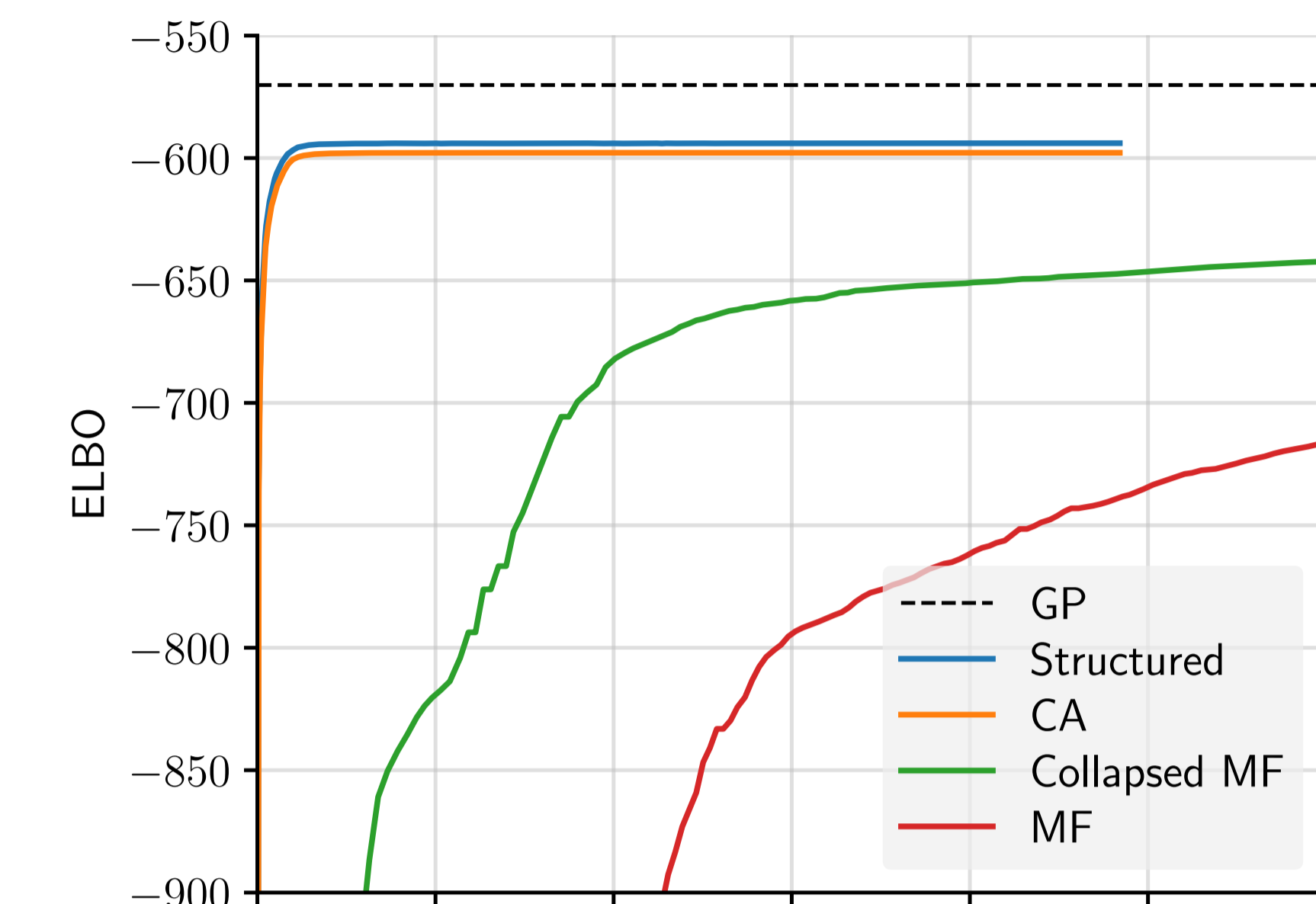
**Insight:**  $q^*(\mathbf{z} | \mathbf{u})$  and  $q^*(\mathbf{u} | \mathbf{z})$  are Gaussian!

**Gibbs sampler:** initial  $\mathbf{u}^{(0)} \sim p(\mathbf{u})$  and iterate

$$\mathbf{z}^{(i)} \sim q^*(\mathbf{z} | \mathbf{u}^{(i-1)}),$$

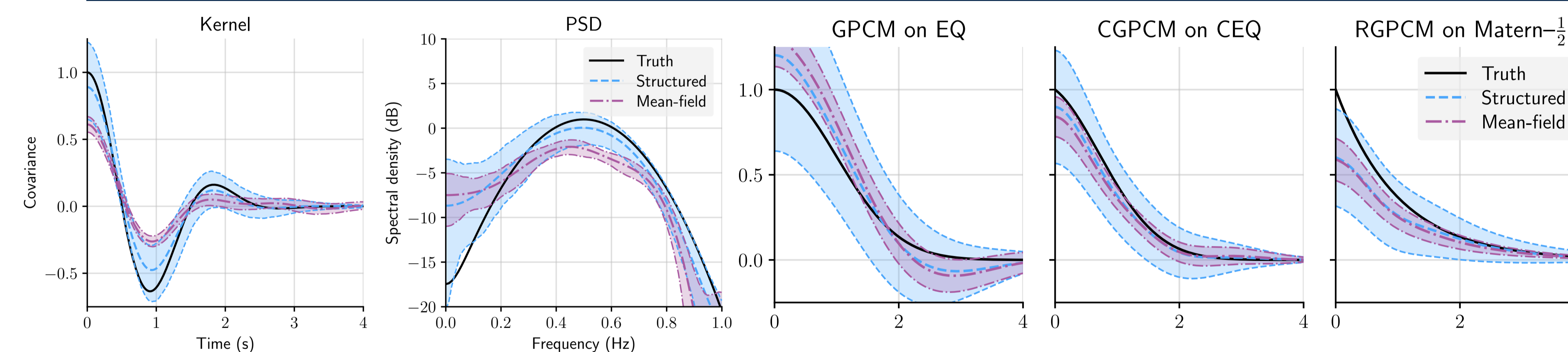
$$\mathbf{u}^{(i)} \sim q^*(\mathbf{u} | \mathbf{z}^{(i)}).$$

Optimise  $\theta$  with SGD on  $\mathcal{F}_{\theta}(q^*(\mathbf{u}, \mathbf{z}))$ .



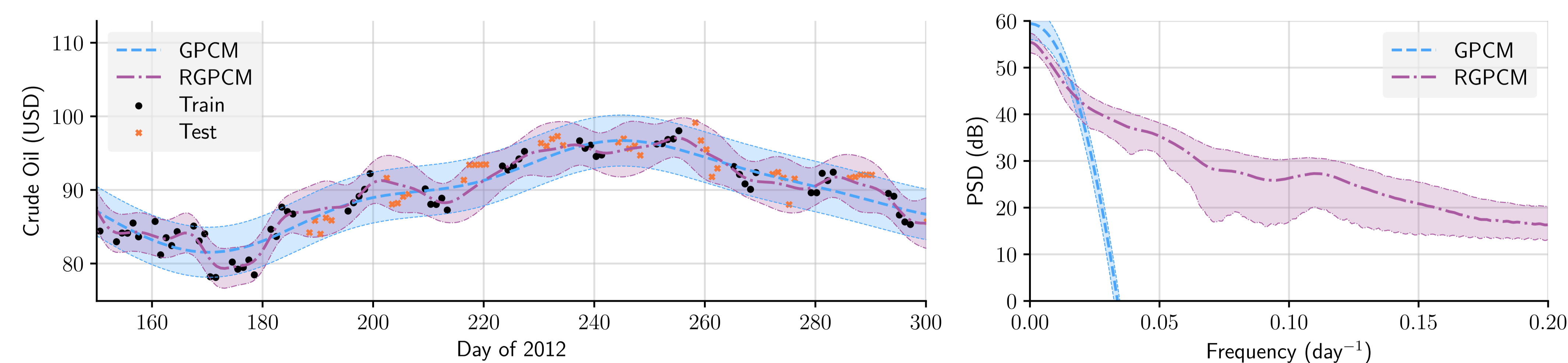
Reconstruction of known model:  $\mathcal{F}$  during optimisation of GPCMs. Mean-field (MF), collapsed MF, coordinate-ascent (CA) and our Gibbs sampler (structured); (GP) is truth.

## Approximation quality of inference schemes



⇒ Structured approximation produces significantly improved uncertainty estimates.

## Prediction of crude oil prices



⇒ GPCM oversmooths, whereas RGPCM captures signal and predicts expressive spectral content.

## Links and references

Code:  
[github.com](https://github.com/wesselb/gpcm)  
[/wesselb/gpcm](https://github.com/wesselb/gpcm)

- [1] Felipe Tobar, Thang D. Bui, and Richard E. Turner. Learning stationary time series using Gaussian processes with nonparametric kernels. *Advances in Neural Information Processing Systems*, 29:3501–3509, 2015.
- [2] James Hensman, Nicolas Durrande, and Arno Solin. Variational fourier features for Gaussian processes. *Journal of Machine Learning Research*, 18(151):1–52, 2018.